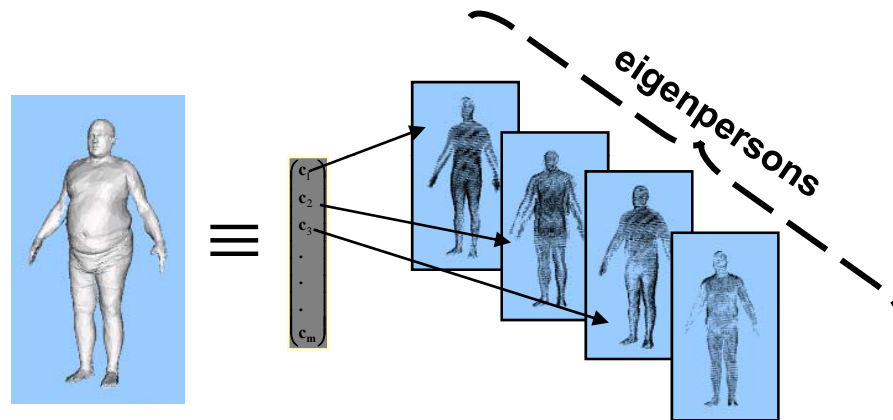


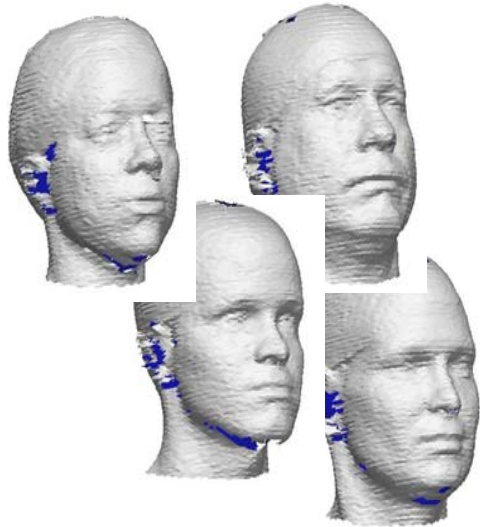
# Statistical Shape Analysis



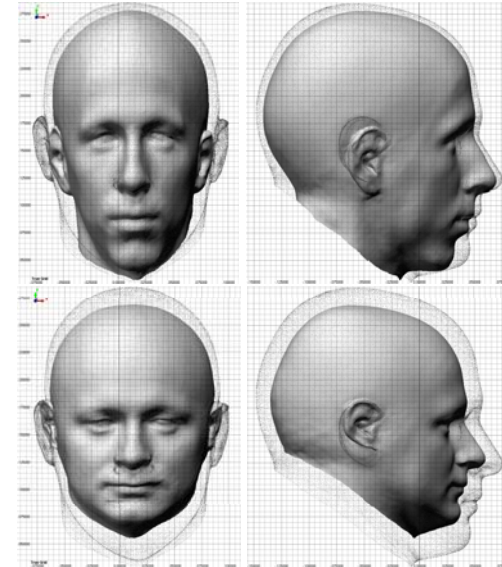
Chang Shu  
National Research Council Canada

# Building statistical models

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Class-specific data



Shape variability

Applications:

Recognition	Reconstruction	Pose determination
Segmentation	Motion analysis	Ergonomic design

# What is SHAPE?

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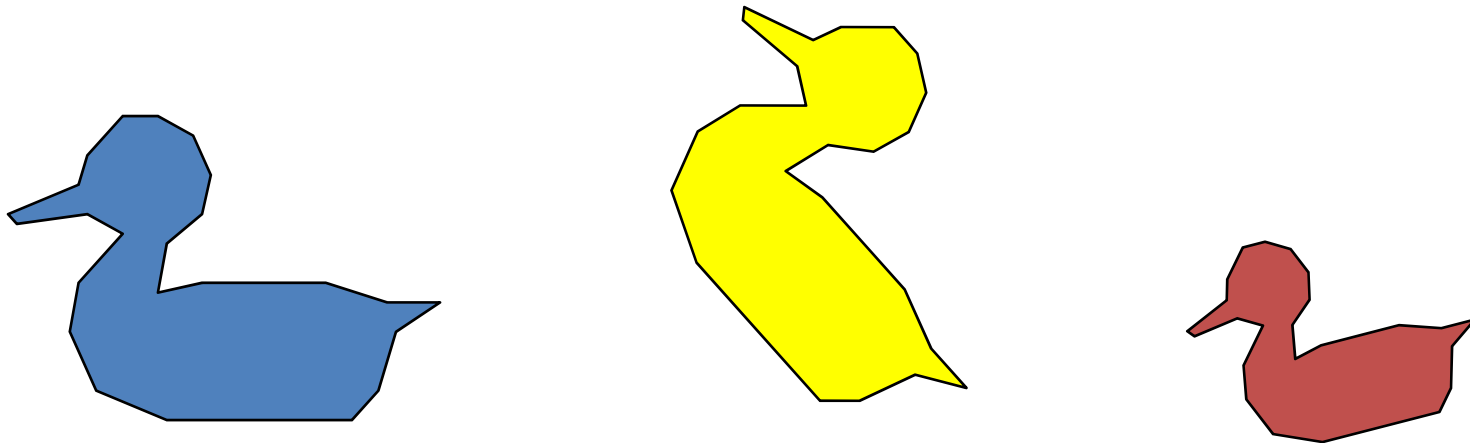
- In everyday language, we often describe shape by analogy
  - For example, “Italy is boot-shaped”
  - Many applications demand a more rigorous and quantitative account of shape
-

# Shape definition

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Shape is all the geometric information that remains when location, scale, and rotational effects are filtered out from an object.

(Kendall 1977)



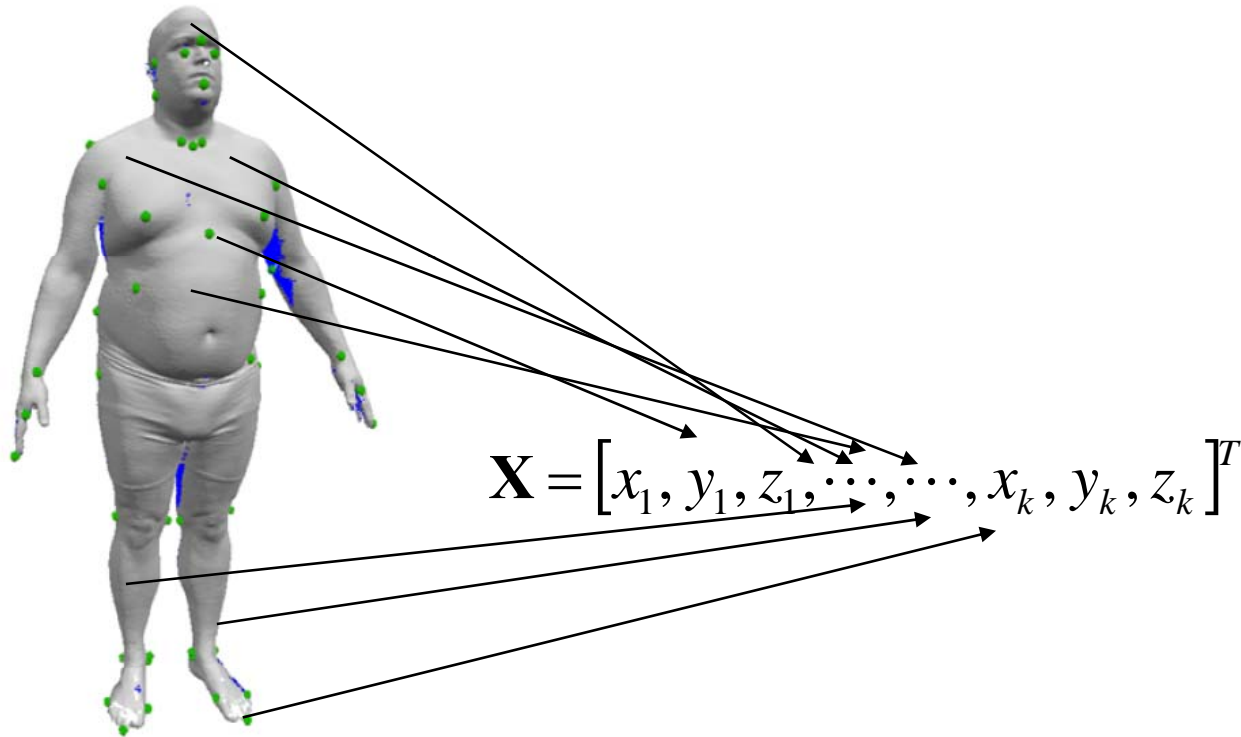
# Statistical Shape Analysis

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- A theory of shape
  - Statistics + Geometry
  - Also called *Geometric Morphometrics* in biological sciences
  - Studies patterns of change in shape
  - Essential part of many techniques in computer vision: active shape model, morphable model, eigenface, etc.
-

# Shape measurement: dense surface data

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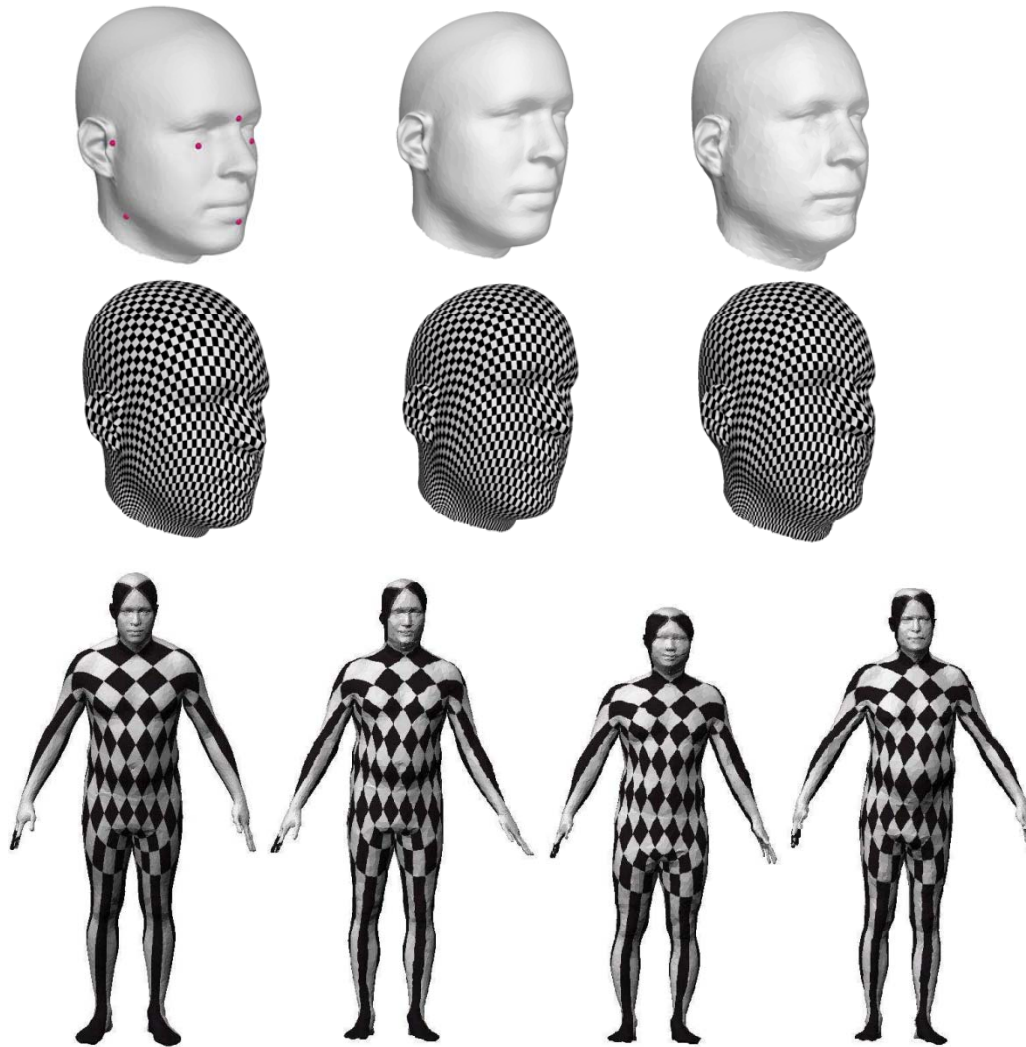


$k \approx 100,000 - 300,000$

---

# Data parameterization

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# Statistics of shape

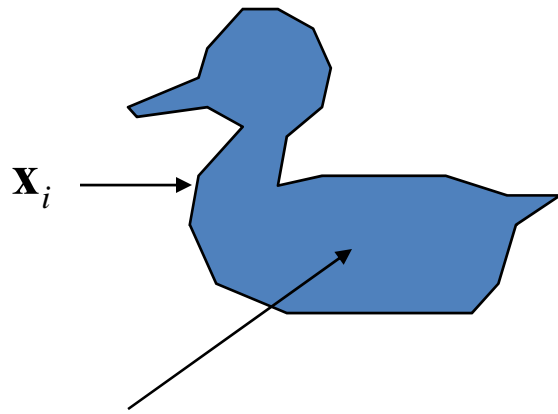
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- Mean shape
  - Variations of shape
  - Shape deformation
  - Dimensionality reduction
  - Factor analysis
-



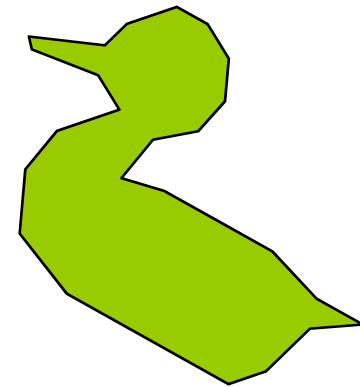
# Centring

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$$\frac{1}{n} \sum \mathbf{x}_i$$

$$\mathbf{x}_i \leftarrow \mathbf{x}_i - \frac{1}{n} \sum \mathbf{x}_i$$



# Removing rotation

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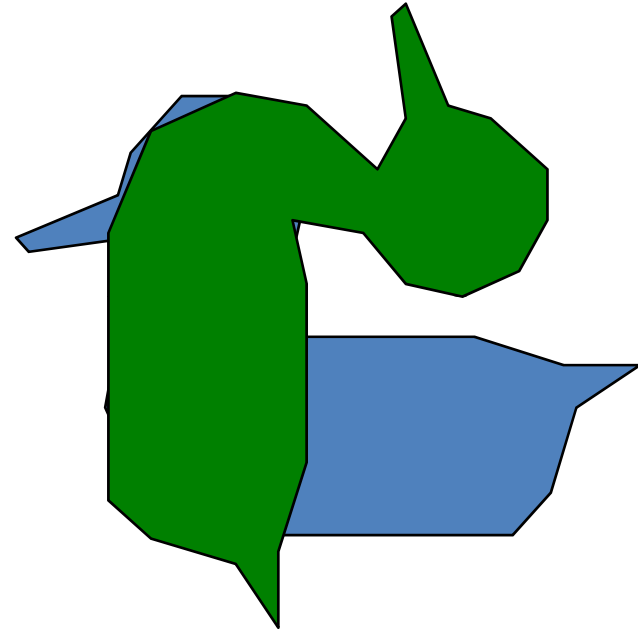
Data matrix

$$\mathbf{Z} = \begin{bmatrix} x_1 & y_1 & z_1 \\ \vdots & \vdots & \vdots \\ x_k & y_k & z_k \end{bmatrix}$$

Singular value decomposition (SVD)

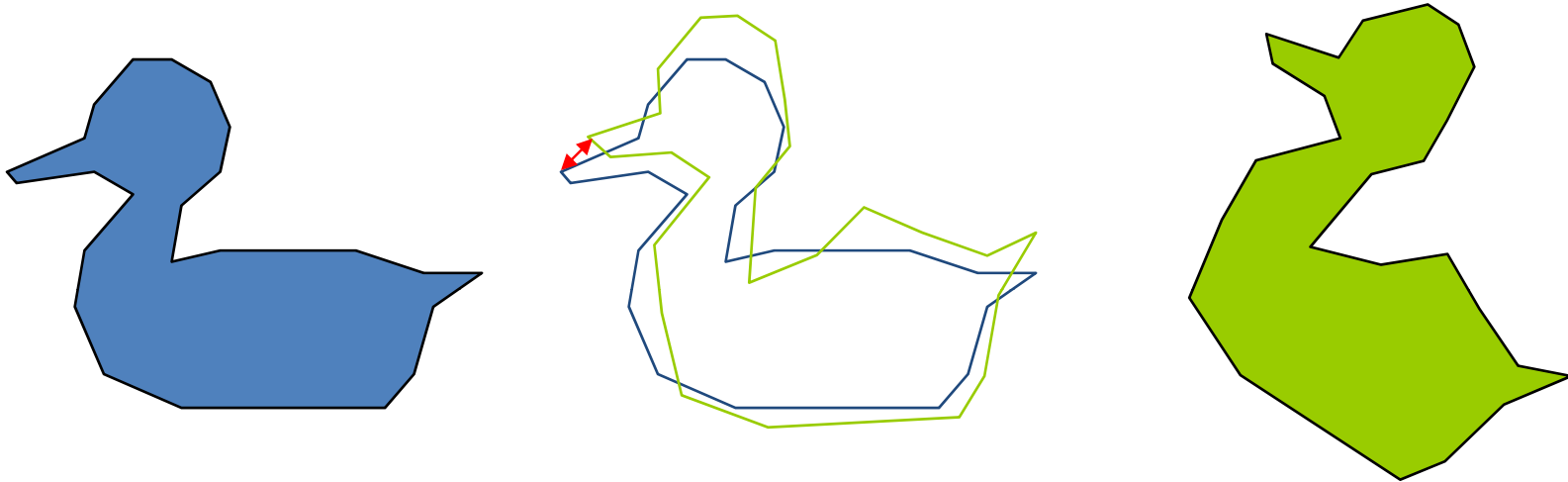
$$\mathbf{Z}_1^T \mathbf{Z}_2 = \mathbf{U} \mathbf{D} \mathbf{V}^T$$

Rotation matrix  $\mathbf{\Gamma} = \mathbf{U} \mathbf{V}^T$



# Distance between two shapes

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Procrustes distance

$$d(\mathbf{Z}_1, \mathbf{Z}_2) = \|\mathbf{Z}_2 - \beta \mathbf{Z}_1 \mathbf{\Gamma}\|$$

$\beta$  is a scale factor. If we want to know size change,  $\beta = 1$

---

# Procrustes Alignment

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Align shapes such that the total Procrustes distance is minimal.

Given shapes  $\mathbf{X}_1, \dots, \mathbf{X}_n$ , the Procrustes mean shape is

$$\mathbf{X}_0 = \arg \min_{\mathbf{X}_0} \sum_{i=1}^n d^2(\mathbf{X}_i, \mathbf{X}_0)$$

---

# Procrustes alignment algorithm

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1. Choose an arbitrary shape as the mean shape  $\mathbf{X}_0$
2. Align the rest of the shapes to  $\mathbf{X}_0$

$$\mathbf{X}_i^p = \mathbf{X}_i \mathbf{\Gamma}_i$$

3. Set new  $\mathbf{X}_0$  to the average of the Procrustes-aligned shapes

$$\mathbf{X}_0 = \frac{1}{n} \sum_{i=1}^n \mathbf{X}_i^p$$

4. Repeat step 2 and 3 until  $\mathbf{X}_0$  is stabilized.
-

# Modeling shape variation

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Average shape

$$\bar{\Psi} = \frac{1}{N} \sum_{i=1}^N \Psi_i$$

Difference vectors

$$\Phi_i = \Psi_i - \bar{\Psi} \quad \mathbf{A} = [\Phi_1 \Phi_2 \cdots \Phi_N]$$

Covariance matrix

$$\Sigma = \frac{1}{N-1} \mathbf{A} \mathbf{A}^T = \frac{1}{N-1} \sum_{i=1}^N \Phi_i \Phi_i^T$$

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# Principal Component Analysis

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Eigen analysis

$$\mathbf{\Sigma} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T$$

Basis transformation

$$\mathbf{b}_i = \mathbf{U}^T \mathbf{\Phi}_i$$
$$\mathbf{\Psi}_i = \overline{\mathbf{\Psi}} + \mathbf{U} \mathbf{b}_i$$

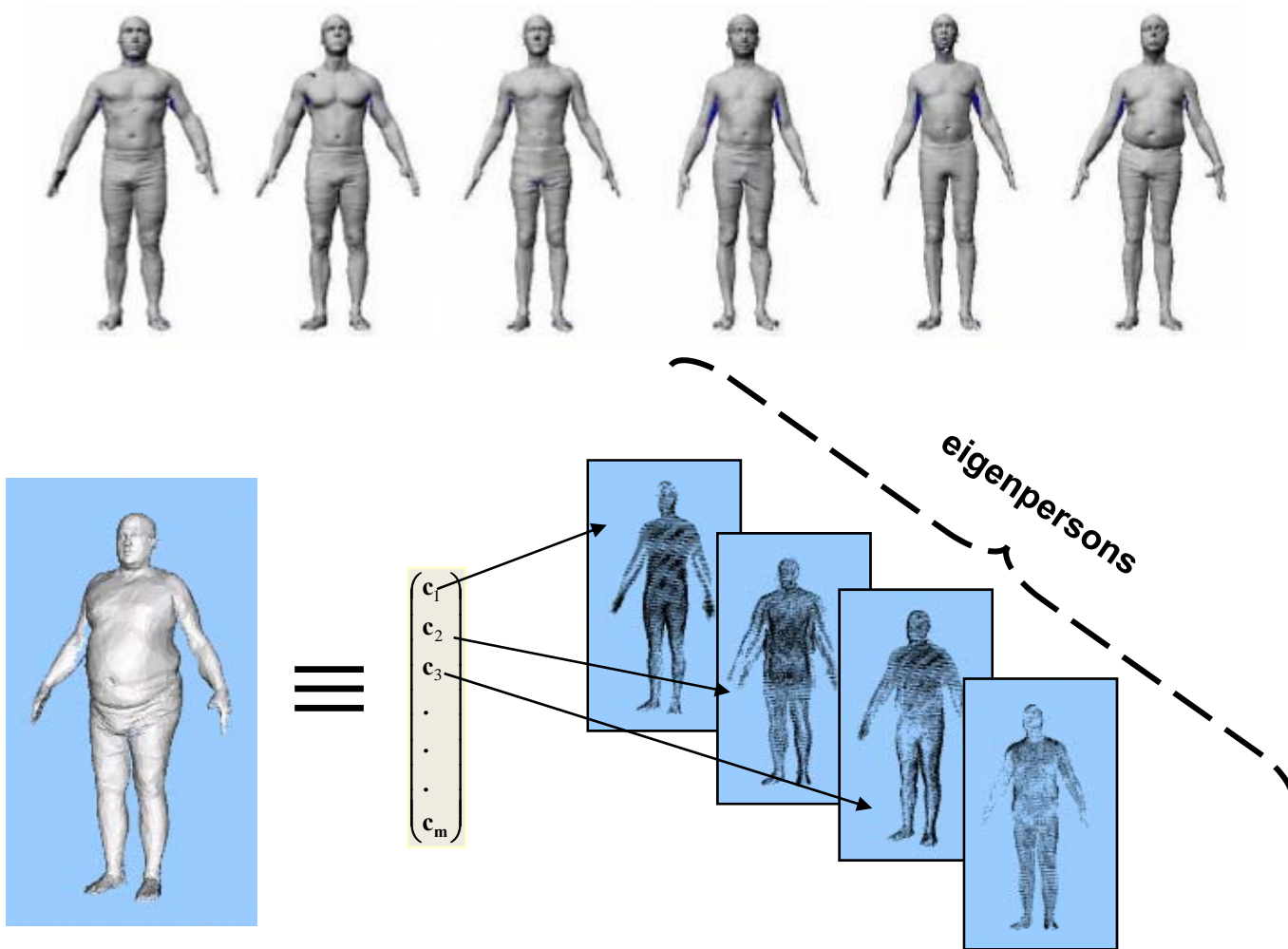
Dimensionality reduction

$$\mathbf{\Psi}_i = \overline{\mathbf{\Psi}} + \sum_{j=1}^M b_j \mathbf{u}_j \quad M \ll N$$

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# Shape decomposition

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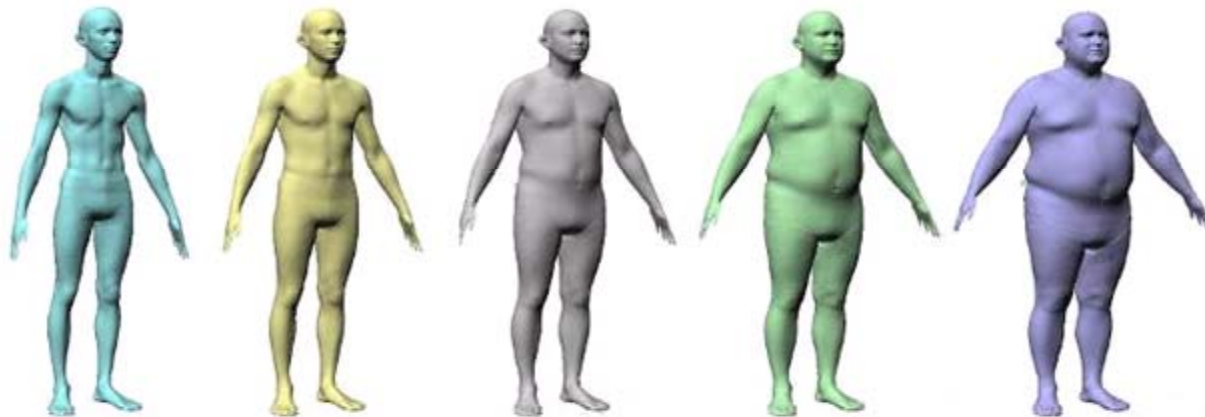
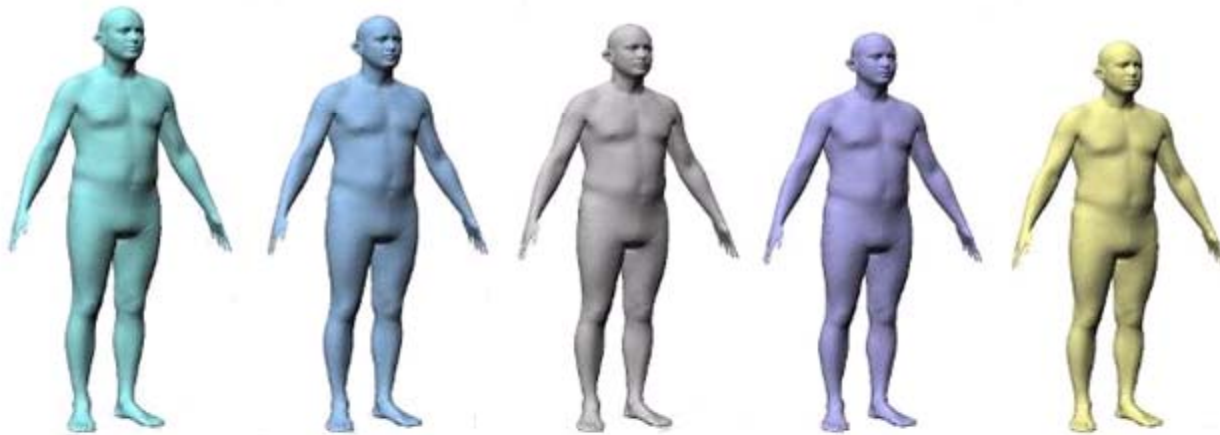


Principal Component Analysis



# Main modes of variation

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Data from CAESAR dataset

# Re-generating a population

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$$\tilde{\Psi} = \bar{\Psi} + \sum_{j=1}^M b_j \mathbf{u}_j$$

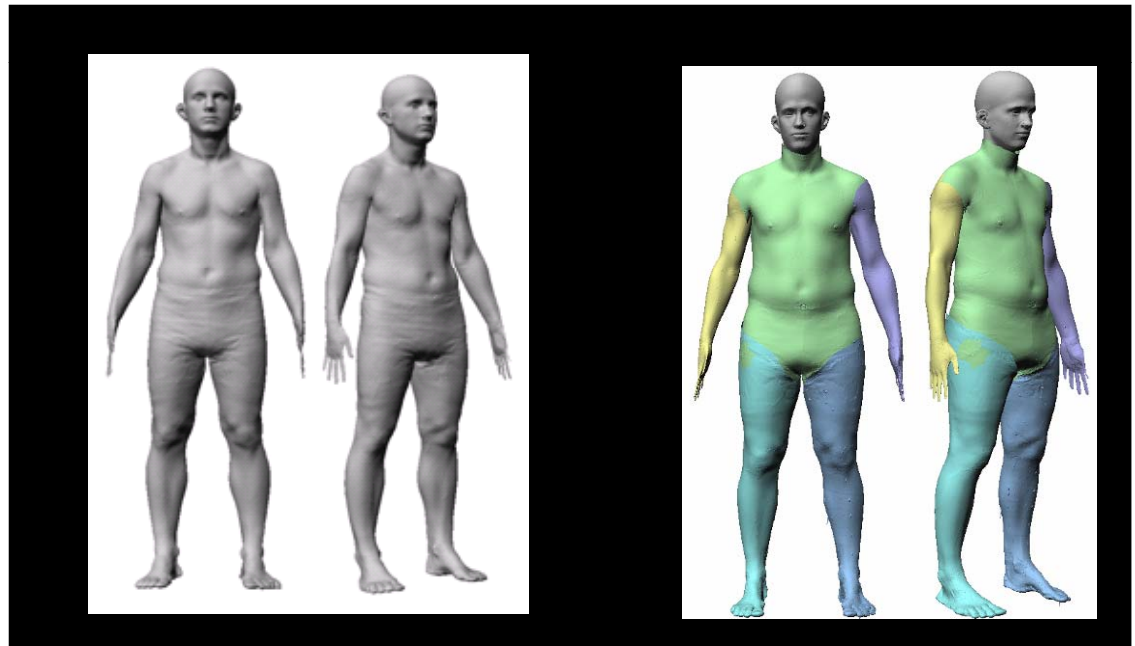
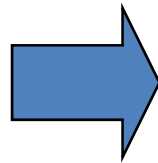
Potential use in simulation, crowd generation, forensics, etc.

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# Image-based Reconstruction

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Reconstruction from single front-view image



# Summary

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Statistical shape analysis offers a mathematical quantification of shape

- Applied to dense surface data
    - Captures detailed shape change
    - Intuitive visualization
    - Reveals new patterns of change in shape
  - More challenges in geometry processing
-

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