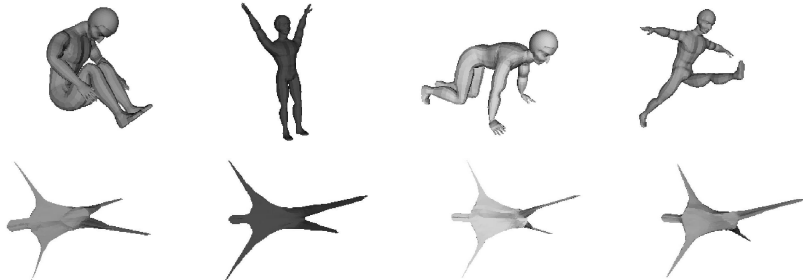


Multi-Dimensional Scaling and Applications to Posture-Invariant Surface Processing

Stefanie Wuhrer



Outline

- ▶ Multi-Dimensional Scaling (MDS)
- ▶ Isometric Embeddings
- ▶ Applications of Isometric Embeddings
 - ▶ Surface Recognition
 - ▶ Face Recognition
 - ▶ Surface Correspondence
 - ▶ Feature Extraction
- ▶ Limitations of Isometric Embeddings

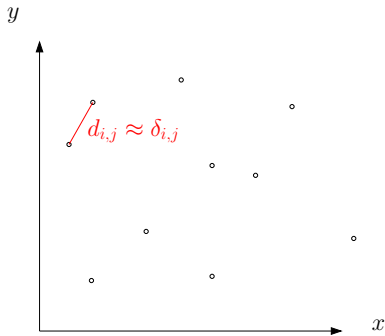
What is MDS?

Given:

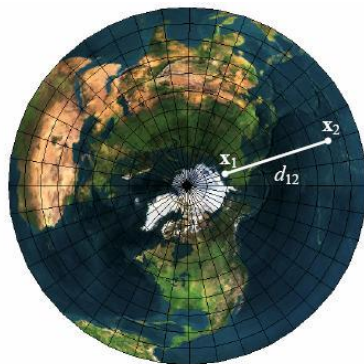
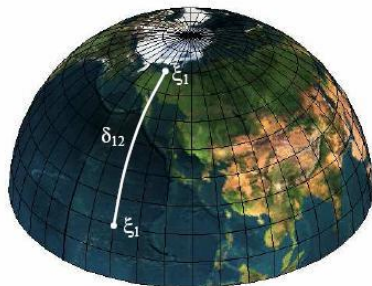
Dissimilarity matrix

$$\Delta = \begin{bmatrix} \delta_{1,1} & \dots & \delta_{1,n} \\ \dots & \dots & \dots \\ \delta_{n,1} & \dots & \delta_{n,n} \end{bmatrix}$$

Find: $X = x_1, x_2, \dots, x_n \in \mathbb{R}^p$



Exact Solution Does Not Exist



⇒ Approximation required (Figure from [BBKY06])

Properties of Approximation

- ▶ Approximation known to be hard
- ▶ Objective function is nonlinear and non-convex
- ▶ Function, gradient, and Hessian require heavy computation
- ▶ Hessian is dense
- ▶ Solution is not unique (translation, rotation, reflections do not change value of stress function)

Methods for MDS

- ▶ Classical MDS [[Gow66](#)] (spectral method)
- ▶ Least-squares MDS [[CC01](#)] (gradient descent method)
- ▶ Fast MDS [[FL95](#)] (heuristic based on projecting points to hyperplanes)
- ▶ Generalized MDS [[BBK06](#)] (embedding space is an arbitrary surface)
- ▶ Many more methods, see Cox and Cox [[CC01](#)]

Extrinsic vs. Intrinsic Geometry

Extrinsic geometry

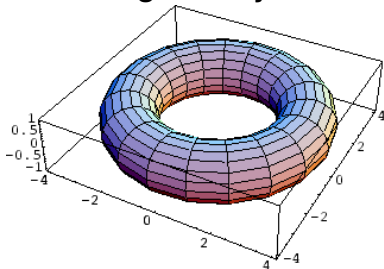
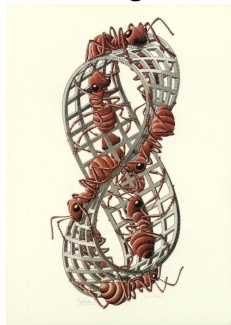


Figure created with Mathematica

Intrinsic geometry



Escher's Moebius strip

Isometry



Figure from [EK03]

S, Q : smooth Riemann
manifolds
Mapping

$$\varphi : S \rightarrow Q$$

isometry if and only if
geodesic distances are
preserved.

Isometric Embedding

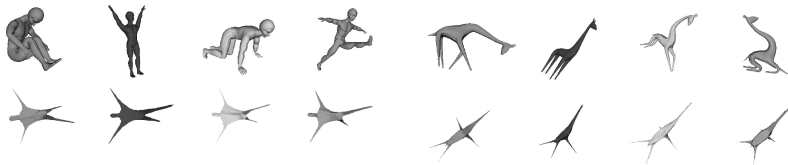
Isometric Embedding

Find a representation of the intrinsic geometry of a Riemannian manifold S in an embedding space Q with simple extrinsic geometry (often: \mathbb{R}^3).

How does MDS help?

We use geodesic distances as dissimilarities.

Surface Recognition [EK03]



Top: original surfaces. Bottom: canonical forms. Figures from [EK03]

Face Recognition [BBK05, BBK03]

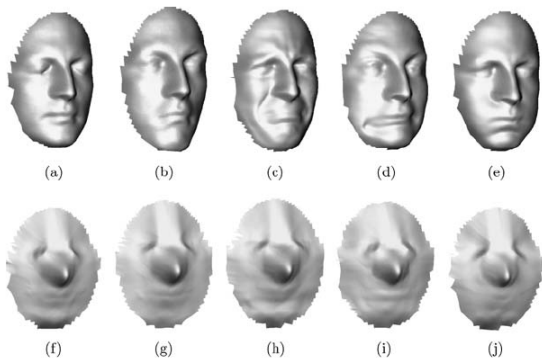
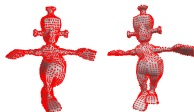


Figure from [BBK05]

Surface Correspondence [WSAB07]

- ▶ Given two incomplete manifold meshes $S^{(0)}$ and $S^{(1)}$



- ▶ Compute a canonical form in \mathbb{R}^k



- ▶ Compute correspondence in MDS space using rigid alignment

Surface Correspondence [BBK06]

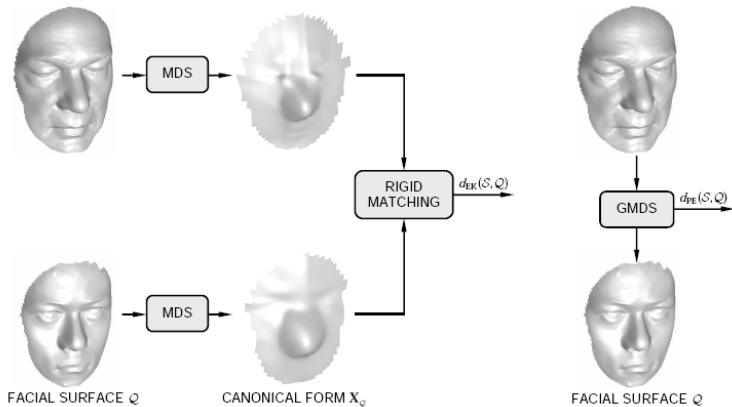
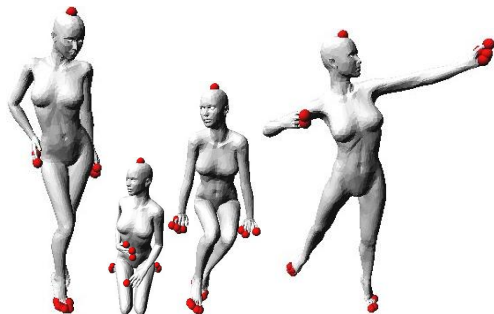


Figure from Bronstein et al. [BBK06].

Feature Extraction [WAS10]

Compute features as points with unusual Spin images [JH99]
on canonical form.



Limitations

- ▶ Symmetric alignments
- ▶ Surfaces with non-Euclidean intrinsic geometries
- ▶ Large holes
- ▶ Outliers

धन्यवाद

Hindi

多謝

Traditional Chinese

ขอบคุณ

Thai

Спасибо

Russian

Gracias

Spanish

شكراً

Arabic

Thank You

Obrigado

Brazilian Portuguese

Grazie

Italian

Danke

German

Merci

French

நன்றி

Tamil

多谢

Simplified Chinese

감사합니다

Korean

ありがとうございました

Japanese



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